## FEATURES

Half-duplex isolated RS-485 transceiver
Integrated oscillator driver for external transformer
PROFIBUS compliant
Complies with ANSI TIA/EIA RS-485-A-1998 and
ISO 8482:1987(E)
16 Mbps data rate
5 V or 3 V operation ( $\mathrm{V}_{\mathrm{DD} 1}$ )
High common-mode transient immunity: > $\mathbf{2 5} \mathbf{~ k V / \mu s}$
Isolated DE OUT status output
Thermal shutdown protection
Safety and regulatory approvals:
UL recognition-2500 V $_{\text {RMs }}$ for 1 minute per UL 1577 (pending)
CSA component acceptance notice \#5A
VDE certificate of conformity
DIN EN 60747-5-2 (VDE 0884 Part 2): 2003-01
DIN EN 60950 (VDE 0805):2001-12; EN 60950: 2000
$V_{\text {IORM }}=560$ V peak
Operating temperature range: $-40^{\circ}$ to $85^{\circ} \mathrm{C}$
Wide body 16 -lead SOIC package

## APPLICATIONS

Isolated RS-485/RS-422 interfaces
PROFIBUS networks
Industrial field networks
Multipoint data transmission systems

## GENERAL DESCRIPTION

The ADM2485 differential bus transceiver is an integrated, galvanically isolated component designed for bidirectional data communication on multipoint bus transmission lines. It is designed for balanced transmission lines and complies with ANSI TIA/EIA RS-485-A-1998 and ISO 8482:1987(E).

The device employs Analog Devices' iCoupler technology to combine a 3-channel isolator, a 3-state differential line driver, and a differential input receiver into a single package. An onchip oscillator outputs a pair of square waveforms which drive an external transformer to provide isolated power with an external transformer. The logic side of the device can be powered with either a 5 V or a 3 V supply while the bus side is powered with an isolated 5 V supply.

The ADM2485 driver has an active high enable. The driver differential outputs and the receiver differential inputs are connected internally to form a differential input/output port that imposes minimal loading on the bus when the driver is disabled or when $V_{D D 1}$ or $V_{D D 2}=0 \mathrm{~V}$. Also provided is an active high receiver disable that causes the receive output to enter a high impedance state.

The device has current-limiting and thermal shutdown features to protect against output short circuits and situations where bus contention might cause excessive power dissipation. The part is fully specified over the industrial temperature range and is available in a 16-lead wide-body SOIC package.

FUNCTIONAL BLOCK DIAGRAM


Figure 1

## Rev.Prl

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[^0]
## SPECIFICATIONS

$2.7 \leq \mathrm{V}_{\mathrm{DD} 1} \leq 5.5 \mathrm{~V}, 4.75 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 2} \leq 5.25 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 1.

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |
| Differential Outputs |  |  |  |  |  |
| Differential Output Voltage, $\mathrm{V}_{\text {OD }}$ |  |  | 5 | V | $\mathrm{R}=\infty$, Figure 3 |
|  | 2.1 |  | 5 | V | $R=50 \Omega$ (RS-422), Figure 3 |
|  | 2.1 |  | 5 | V | $R=27 \Omega$ (RS-485), Figure 3 |
|  | 2.1 |  | 5 | V | $V_{\text {TST }}=-7 \mathrm{~V} \text { to } 12 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 1} \geq 4.75$ <br> Figure 4 |
| $\Delta \mid$ Vod $\mid$ for Complementary Output States |  |  | 0.2 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$, Figure 3 |
| Common-Mode Output Voltage, Voc |  |  | 3 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$, Figure 3 |
| $\Delta \mid$ Voc $\mid$ for Complementary Output States |  |  | 0.2 | V | $\mathrm{R}=27 \Omega$ or $50 \Omega$, Figure 3 |
| Output Short-Circuit Current, Vout = High | 60 |  | 200 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {Out }} \leq+12 \mathrm{~V}$ |
| Output Short-Circuit Current, Vout = Low | 60 |  | 200 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {Out }} \leq+12 \mathrm{~V}$ |
| Bus Enable Output |  |  |  |  |  |
| Output High Voltage | $\mathrm{V}_{\mathrm{DD} 2}-0.1$ |  |  | V | $\mathrm{l}_{\text {ODE }}=20 \mu \mathrm{~A}$ |
|  | $V_{\text {DD2 }}-0.3$ | $\mathrm{V}_{\mathrm{DD} 2}=0.1$ |  | V | $\mathrm{l}_{\text {Ode }}=1.6 \mathrm{~mA}$ |
|  | VDD2-0.4 | $\mathrm{V}_{\mathrm{DD} 2}-0.2$ |  | V | lode $=4 \mathrm{~mA}$ |
| Output Low Voltage |  |  | 0.1 | V | lode $=-20 \mu \mathrm{~A}$ |
|  |  | 0.1 | 0.3 | V | $\mathrm{l}_{\text {Iode }}=-1.6 \mathrm{~mA}$ |
|  |  | 0.2 | 0.4 | V | $\mathrm{l}_{\text {IDE }}=-4 \mathrm{~mA}$ |
| Logic Inputs |  |  |  |  |  |
| Input High Voltage | $0.7 \mathrm{~V}_{\mathrm{DD} 1}$ |  |  | V | TxD, RTS, $\overline{\mathrm{RE}}$ |
| Input Low Voltage |  |  | $0.25 \mathrm{~V}_{\text {DD } 1}$ | V | TxD, RTS, $\overline{\mathrm{RE}}$ |
| CMOS Logic Input Current (TxD, RTS, $\overline{\mathrm{RE}}$ ) | -10 | 0.01 | 10 | $\mu \mathrm{A}$ | TxD, RTS, $\overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{DD} 1}$ or 0 V |
| RECEIVER |  |  |  |  |  |
| Differential Inputs |  |  |  |  |  |
| Differential Input Threshold Voltage, $\mathrm{V}_{\text {TH }}$ | -200 |  | 200 | mV | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {См }} \leq+12 \mathrm{~V}$ |
| Input Hysteresis |  | 70 |  | mV | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {См }} \leq+12 \mathrm{~V}$ |
| Input Resistance ( $\mathrm{A}, \mathrm{B}$ ) | 20 | 30 |  | $\mathrm{k} \Omega$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {СM }} \leq+12 \mathrm{~V}$ |
| Input Current ( $\mathrm{A}, \mathrm{B}$ ) |  |  | 0.6 | mA | $\mathrm{V}_{\text {IN }}=+12 \mathrm{~V}$ |
|  |  |  | -0.35 | mA | $\mathrm{V}_{\text {IN }}=-7 \mathrm{~V}$ |
| RxD Logic Output: |  |  |  |  |  |
| Output High Voltage | $V_{\text {DD1 }}-0.1$ |  |  | V | lout $=20 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=0.2 \mathrm{~V}$ |
|  | $\mathrm{V}_{\mathrm{DD} 1}-0.4$ | $V_{\text {DD1 }}-0.2$ |  | V | $\mathrm{l}_{\text {OUt }}=4 \mathrm{~mA}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=0.2 \mathrm{~V}$ |
| Output Low Voltage |  |  | 0.1 | V | lout $=-20 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=-0.2 \mathrm{~V}$ |
|  |  | 0.2 | 0.4 | V | lout $=-4 \mathrm{~mA}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=-0.2 \mathrm{~V}$ |
| Output Short Circuit Current | 7 |  | 85 | mA | $\mathrm{V}_{\text {OUT }}=\mathrm{GND}$ or $\mathrm{V}_{\text {cc }}$ |
| Three-State Output Leakage Current |  |  | $\pm 1$ | $\mu \mathrm{A}$ | $0.4 \mathrm{~V} \leq \mathrm{V}_{\text {out }} \leq 2.4 \mathrm{~V}$ |
| Transformer Driver |  |  |  |  |  |
| Oscillator Frequency |  | 500 |  | kHz |  |
| Switch On resistance |  | 0.5 | 1.5 | $\Omega$ |  |
| Start-Up Voltage |  | 2.2 | 2.5 | V |  |

ADM2485

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| POWER SUPPLY CURRENT Logic Side <br> Bus Side |  | 1.0 <br> 4.0 <br> 2.1 <br> 43.0 <br> 58.0 | 1.3 <br> 0.8 <br> 1.1 <br> 3.0 | mA <br> mA <br> mA <br> mA <br> mA <br> mA <br> mA <br> mA <br> mA | $\begin{aligned} & \mathrm{RTS}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 1}=5.5 \mathrm{~V} \\ & 2 \mathrm{Mbps}, \mathrm{~V}_{\mathrm{DD} 1}=5.5 \mathrm{~V} \text {, Figure } 5 \\ & 16 \mathrm{Mbps}, \mathrm{~V}_{\mathrm{DD} 1}=5.5 \mathrm{~V} \text {, Figure } 5 \\ & \mathrm{RTS}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 1}=3 \mathrm{~V} \\ & 2 \mathrm{Mbps}, \mathrm{~V}_{\mathrm{DD} 1}=3 \mathrm{~V} \text {, Figure } 5 \\ & 16 \mathrm{Mbps}, \mathrm{~V}_{\mathrm{DD1} 1}=3 \mathrm{~V} \text {, Figure } 5 \\ & \mathrm{RTS}=0 \mathrm{~V} \\ & 2 \mathrm{Mbps}, \mathrm{RTS}=\mathrm{V}_{\mathrm{DD} 1}, \text { Figure } 5 \\ & 16 \mathrm{Mbps}, \mathrm{RTS}=\mathrm{V}_{\mathrm{DD} 1}, \text { Figure } 5 \end{aligned}$ |
| COMMON-MODE TRANSIENT IMMUNITY ${ }^{1}$ | 25 |  |  | kV/ $\mu \mathrm{s}$ | $\begin{aligned} & \text { VCM }=1 \mathrm{kV} \text {, Transient Magnitude }= \\ & 800 \mathrm{~V} \end{aligned}$ |
| HIGH FREQUENCY COMMON-MODE NOISE IMMUNITY |  | 100 |  | mV | $\begin{aligned} & \mathrm{V}_{\text {HF }}=+5 \mathrm{~V},-2 \mathrm{~V}<\mathrm{V}_{\text {TEST } 2}<7 \mathrm{~V}, \\ & 1<\mathrm{f}_{\text {TEST }}<50 \mathrm{MHz}, \text { Figure } 6 \end{aligned}$ |

${ }^{1} \mathrm{CM}$ is the maximum common-mode voltage slew rate that can be sustained while maintaining specification-compliant operation. $\mathrm{V}_{\mathrm{CM}}$ is the common-mode potential difference between the logic and bus sides. The transient magnitude is the range over which the common-mode is slewed. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

## TIMING SPECIFICATIONS

$2.7 \leq \mathrm{V}_{\mathrm{DD} 1} \leq 5.5 \mathrm{~V}, 4.75 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 2} \leq 5.25 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 2.

| Parameter | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |
| Maximum Data Rate | 16 |  |  | Mbps |  |
| Propagation Delay tplh, $\mathrm{t}_{\text {PhL }}$ | 25 | 45 | 55 | ns | $R_{\text {LIIFF }}=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$; See Figure 7. |
| RTS-to-DE Propagation Delay | 20 | 35 | 55 | ns | See Figure 8. |
| Pulse-Width Distortion, tpwo |  |  | 5 | ns | RLDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$; See Figure 7 and Figure 12. |
| Switching Skew, $\mathrm{t}_{\text {skew }}$ |  | 2 | 5 | ns | RLDIFF $=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$; See Figure 7 and Figure 12. |
| Rise/Fall Time $\mathrm{t}_{\mathrm{R},} \mathrm{t}_{\mathrm{F}}$ |  | 5 | 15 | ns | $R_{\text {LDIFF }}=54 \Omega, C_{L 1}=C_{L 2}=100 \mathrm{pF}$; See Figure 7 and Figure 12. |
| Enable Time |  | 43 | 53 | ns | See Figure 9 and Figure 14. |
| Disable Time |  | 43 | 55 | ns | See Figure 9 and Figure 14. |
| Enable Skew, $\left\|\mathrm{t}_{\text {AzH }}-\mathrm{t}_{\text {BzL }}\right\|,\left\|\mathrm{t}_{\text {Azl }}-\mathrm{t}_{\text {BzH }}\right\|$ |  | 1 | 3 | ns | See Figure 9 and Figure 14. |
| Disable Skew, $\left\|\mathrm{t}_{\text {AHz }}-\mathrm{tblz}\right\|,\left\|\mathrm{t}_{\text {ALZ }}-\mathrm{t}_{\text {BHZ }}\right\|$ |  | 2 | 5 | ns | See Figure 9 and Figure 14. |
| RECEIVER |  |  |  |  |  |
| Propagation Delay tplh, $\mathrm{t}_{\text {PHL }}$ | 25 | 45 | 55 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$; See Figure 10 and Figure 13. |
| Differential Skew $\mathrm{tskew}^{\text {che }}$ |  |  | 5 | ns | $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$; See Figure 10 and Figure 13. |
| Enable Time |  | 3 | 13 | ns | $\mathrm{RL}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$; See Figure 11 and |
|  |  |  |  |  | Figure 15. |
| Disable Time |  | 3 | 13 | ns | $R_{L}=1 \mathrm{k} \Omega, C_{L}=15 \mathrm{pF}$; See Figure 11 and Figure 15. |

## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted. All voltages are relative to their respective ground.
Table 3.

| Parameter | Rating |
| :--- | :--- |
| $\mathrm{V}_{\mathrm{DD} 1}$ | -0.5 V to +6 V |
| $\mathrm{~V}_{\mathrm{DD} 2}$ | -0.5 V to +6 V |
| Digital Input Voltage (RTS, $\overline{\mathrm{RE}, \mathrm{TxD})}$ | -0.5 V to $\mathrm{V}_{\mathrm{DD} 1}+0.5 \mathrm{~V}$ |
| Digital Output Voltage |  |
| RxD | -0.5 V to $\mathrm{V}_{\mathrm{DD} 1}+0.5 \mathrm{~V}$ |
| DE OUT | -0.5 V to $\mathrm{V}_{\mathrm{DD} 2}+0.5 \mathrm{~V}$ |
| Driver Output/Receiver Input Voltage | -9 V to +14 V |
| Operating Temperature Range | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Average Output Current per Pin | -35 mA to +35 mA |
| $\theta_{\mathrm{JA}}$ Thermal Impedance | $73^{\circ} \mathrm{C} / \mathrm{W}$ |
| Lead Temperature |  |
| $\quad$ Soldering (10 sec) | $300^{\circ} \mathrm{C}$ |
| Vapour Phase ( 60 sec ) | $215^{\circ} \mathrm{C}$ |
| Infrared (15 sec) | $220^{\circ} \mathrm{C}$ |

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ESD CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

## ADM2485E CHARACTERISTICS

## PACKAGE CHARACTERISTICS

Table 2.

| Parameter | Symbol | Min | Typ $\quad$ Max | Unit | Test Conditions |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Resistance (Input-Output) ${ }^{1}$ | $\mathrm{R}_{-\mathrm{o}}$ | $10^{12}$ | $\Omega$ |  |  |
| Capacitance (Input-Output) $^{1}$ | $\mathrm{C}_{1-\mathrm{O}}$ | 3 | pF | $\mathrm{f}=1 \mathrm{MHz}$ |  |
| Input Capacitance ${ }^{2}$ | $\mathrm{C}_{1}$ | 4 | pF |  |  |
| Input IC Junction-to-Case Thermal Resistance | $\theta_{\mathrm{JCI}}$ | 33 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ | Thermocouple located at |  |
| Output IC Junction-to-Case Thermal Resistance | $\theta_{\mathrm{Jco}}$ |  | 28 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ | center of package underside |

${ }^{1}$ Device considered a two-terminal device: Pins $1,2,3,4,5,6,7$, and 8 shorted together, and Pins $9,10,11,12,13,14,15$, and 16 shorted together.
${ }^{2}$ Input capacitance is from any input data pin to ground.

## REGULATORY INFORMATION

The ADM2485 is to be approved by the following organizations:
Table 3.

| Organization | Approval Type | Notes |
| :--- | :--- | :--- |
| UL | To be recognized under 1577 component recognition program. | In accordance with UL1577, each ADM2485 <br> is proof-tested by applying an insulation <br> test voltage $\geq 3000 \mathrm{Vrms} \mathrm{for} 1$ second (current <br> leakage detection limit $=5 \mu \mathrm{~A})$. |
| CSA | To be approved under CSA Component Acceptance Notice \#5A. <br> VDE | To be certified according to DIN EN 60747-5-2 (VDE 0884 Part 2): 2003-01 |
|  |  | In accordance with VDE 0884, each ADM2485 <br> is proof-tested by applying an insulation <br> test voltage $\geq 1050$ VPEAK for 1 second <br> (partial discharge detection limit $=5$ pC). |

INSULATION AND SAFETY-RELATED SPECIFICATIONS
Table 4.

| Parameter | Symbol | Value | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: |
| Rated Dielectric Insulation Voltage |  | 2500 | V rms | 1-minute duration. |
| Minimum External Air Gap (Clearance) | L(101) | 5.15 min | mm | Measured from input terminals to output terminals, shortest distance through air. |
| Minimum External Tracking (Creepage) | L(102) | 5.5 min | mm | Measured from input terminals to output terminals, shortest distance along body. |
| Minimum Internal Gap (Internal Clearance) |  | 0.017 min | mm | Insulation distance through insulation. |
| Tracking Resistance (Comparative Tracking Index) | CTI | >175 | V | DIN IEC 112/VDE 0303 Part 1. |
| Isolation Group |  | Illa |  | Material Group (DIN VDE 0110, 1/89,). |

## VDE 0884 INSULATION CHARACTERISTICS

This isolator is suitable for basic electrical isolation only within the safety limit data. Maintenance of the safety data must be ensured by means of protective circuits.

An asterisk (*) on packages denotes VDE 0884 approval for 560 V peak working voltage.
Table 5.

| Description | Symbol | Characteristic | Unit |
| :---: | :---: | :---: | :---: |
| Installation classification per DIN VDE 0110 for rated mains voltage |  |  |  |
| $\leq 150 \mathrm{~V}$ rms |  | I to IV |  |
| $\leq 300 \mathrm{~V}$ rms |  | I to III |  |
| $\leq 400 \mathrm{~V}$ rms |  | I to II |  |
| Climatic classification |  | 40/85/21 |  |
| Pollution degree (DIN VDE 0110, Table 1) |  | 2 |  |
| Maximum working insulation voltage | VIorm | 560 | $V_{\text {PeAK }}$ |
| Input to output test voltage, Method b1 | $V_{\text {PR }}$ | 1050 | $V_{\text {Peak }}$ |
| $\mathrm{V}_{\text {IORM }} \times 1.875=\mathrm{V}_{\text {PR, }} 100 \%$ production tested, $\mathrm{t}_{\mathrm{m}}=1 \mathrm{sec}$, partial discharge $<5 \mathrm{pC}$ |  |  |  |
| Input to output test voltage, Method a <br> (After environmental tests, Subgroup 1) |  |  |  |
| $\mathrm{V}_{\text {IORM }} \times 1.6=\mathrm{V}_{\text {PR, }} \mathrm{t}_{\mathrm{m}}=60 \mathrm{sec}$, partial discharge $<5 \mathrm{pC}$ (After input and/or safety test, Subgroup 2/3) |  | 896 | $V_{\text {peak }}$ |
| $\mathrm{V}_{\text {IORM }} \times 1.2=\mathrm{V}_{\text {PR, }}, \mathrm{t}_{\mathrm{m}}=60 \mathrm{sec}$, partial discharge $<5 \mathrm{pC}$ | $V_{\text {PR }}$ | 672 | $V_{\text {Peak }}$ |
| Highest allowable overvoltage <br> (Transient overvoltage, $\mathrm{t}_{\mathrm{TR}}=10 \mathrm{sec}$ ) | $V_{\text {TR }}$ | 4000 | $V_{\text {Peak }}$ |
| Safety-limiting values (maximum value allowed in the event of a failure. See thermal derating curve) |  |  |  |
| Case temperature | Ts | 150 | ${ }^{\circ} \mathrm{C}$ |
| Input current | Is, input | 265 | mA |
| Output current | IS, output | 335 | mA |
| Insulation resistance at Ts, $\mathrm{V}_{10}=500 \mathrm{~V}$ | Rs | $>10^{9}$ | $\Omega$ |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Table 4.

| Pin | Mnemonic | Function |
| :---: | :---: | :---: |
| 1 | D1 | Transformer driver terminal 1. |
| 2 | D2 | Transformer driver terminal 2. |
| 3 | $\mathrm{GND}_{1}$ | Ground, Logic Side. |
| 4 | $\mathrm{V}_{\mathrm{DD} 1}$ | Power Supply Logic Side, 3 V or 5 V . Decoupling capacitor to $\mathrm{GND}_{1}$ required, capacitor value should be between $0.01 \mu \mathrm{~F}$ and $0.1 \mu \mathrm{~F}$. |
| 5 | RxD | Receiver Output data. This output is high when $(A-B)>200 \mathrm{mV}$, and low when $(A-B)<-200$ mV . The output is tri-stated when the receiver is disabled, i.e. when $\overline{\mathrm{RE}}$ is driven high. |
| 6 | $\overline{\mathrm{RE}}$ | Receiver Enable input. This is an active-low input. Driving this input low enables the receiver, while driving it high disables the receiver. |
| 7 | RTS | Driver enable input. Driving this input high enables the driver, while driving it low disables the driver. |
| 8 | TxD | Driver input. Data to be transmitted by the driver is applied to this input. |
| 10 | DE OUT | Driver Enable status output |
| 12 | A | Noninverting Driver Output/Receiver Input. When the driver is disabled or $V_{D D 1}$ or $V_{D D 2}$ is powered down, pin A is put in a high impedance state to avoid overloading the bus. |
| 13 | B | Inverting Driver Output/Receiver Input. When the driver is disabled or $\mathrm{V}_{\mathrm{DD} 1}$ or $\mathrm{V}_{\mathrm{DD} 2}$ is powered down, pin $B$ is put in a high impedance state to avoid overloading the bus. |
| 9,11,14,15 | $\mathrm{GND}_{2}$ | Ground, Bus Side. |
| 16 | $\mathrm{V}_{\mathrm{DD} 2}$ | Power Supply Bus Side, Isolated 5 V supply. Decoupling capacitor to $\mathrm{GND}_{2}$ required, capacitor value should be between $0.01 \mu \mathrm{~F}$ and $0.1 \mu \mathrm{~F}$. |

## TEST CIRCUITS



Figure 3. Driver Voltage Measurement


Figure 4. Driver Voltage Measurement


Figure 5. Supply-Current Measurement Test Circuit


Figure 6. High Frequency Common-Mode Noise Test Circuit


Figure 7. Driver Propagation Delay


Figure 8. RTS to DE OUT Propagation Delay


Figure 9. Driver Enable/Disable


Figure 10. Receiver Propagation Delay


Figure 11. Receiver Enable/Disable

## Preliminary Technical Data

## SWITCHING CHARACTERISTICS



Figure 12. Driver Propagation Delay, Rise/Fall Timing


Figure 13. Receiver Propagation Delay


Figure 14. Driver Enable/Disable Timing


Figure 15. Receiver Enable/Disable Timing

## CIRCUIT DESCRIPTION

## ELECTRICAL ISOLATION

In the ADM2485, electrical isolation is implemented on the logic side of the interface. Therefore, the part has two main sections: a digital isolation section and a transceiver section (see Figure 16). Driver input and data enable, applied to the TxD and RTS pins, respectively, and referenced to logic ground $\left(\mathrm{GND}_{1}\right)$, are coupled across an isolation barrier to appear at the transceiver section referenced to isolated ground $\left(\mathrm{GND}_{2}\right)$. Similarly, the receiver output, referenced to isolated ground in the transceiver section, is coupled across the isolation barrier to appear at the RxD pin referenced to logic ground.

## iCoupler Technology

The digital signals are transmitted across the isolation barrier using $i$ Coupler technology. This technique uses chip scale transformer windings to couple the digital signals magnetically from one side of the barrier to the other. Digital inputs are encoded into waveforms that are capable of exciting the primary transformer winding. At the secondary winding, the induced waveforms are then decoded into the binary value that was originally transmitted.


Figure 16. ADM2485 Digital Isolation and Transceiver Sections

## TRUTH TABLES

The truth tables in this section use these abbreviations:

| Letter | Description |
| :--- | :--- |
| H | High level |
| I | Indeterminate |
| L | Low level |
| X | Irrelevant |
| Z | High impedance (off) |
| NC | Disconnected |

Table 6. Transmitting

| Supply Status |  | Inputs |  | Output |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VDD1 | VDD2 | RTS | TxD | A | B | DE OUT |
| On | On | H | H | H | L | H |
| On | On | H | L | L | H | H |
| On | On | L | X | Z | Z | L |
| On | Off | X | x | Z | Z | L |
| Off | On | X | X | Z | Z | L |
| Off | Off | X | X | Z | Z | L |

Table 7. Receiving

| Supply Status |  |  |  | Inputs |  | Output |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: |
| $\mathbf{V}_{\text {DD } 1}$ | $\mathbf{V}_{\text {DD } 2}$ | $\mathbf{A - B}(\mathbf{V})$ | $\overline{\mathbf{R E}}$ | RxD |  |  |
| On | On | $>0.2$ | L or NC | H |  |  |
| On | On | $<-0.2$ | L or NC | L |  |  |
| On | On | $-0.2<\mathrm{A}-\mathrm{B}<0.2$ | L or NC | I |  |  |
| On | On | Inputs open | L or NC | H |  |  |
| On | On | X | H | Z |  |  |
| On | Off | X | L or NC | H |  |  |
| Off | On | X | or NC | H |  |  |
| Off | Off | X | L or NC | L |  |  |

## THERMAL SHUTDOWN

The ADM2485 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. The thermal sensing circuitry detects the increase in die temperature under this condition and disables the driver outputs. This circuitry is designed to disable the driver outputs when a die temperature of $150^{\circ} \mathrm{C}$ is reached. As the device cools, the drivers are re-enabled at a temperature of $140^{\circ} \mathrm{C}$.

## RECEIVER FAIL-SAFE INPUTS

The receiver input includes a fail-safe feature that guarantees a logic high RxD output when the A and B inputs are floating or open-circuited.

## MAGNETIC FIELD IMMUNITY

Because iCouplers use a coreless technology, no magnetic components are present, and the problem of magnetic saturation of the core material does not exist. Therefore, $i$ Couplers have essentially infinite dc field immunity. The analysis below defines the conditions under which this may occur. The ADM2485's 3 V operating condition is examined because it represents the most susceptible mode of operation.

The limitation on the iCoupler's ac magnetic field immunity is set by the condition in which the induced error voltage in the receiving coil (the bottom coil in this case) is made sufficiently large, either to falsely set or reset the decoder. The voltage induced across the bottom coil is given by

$$
V=\left(\frac{-d \beta}{d t}\right) \sum \pi r_{n}^{2} ; n=1,2, \ldots, N
$$

where, if the pulses at the transformer output are greater than 1.0 V in amplitude:
$\beta=$ magnetic flux density (gauss)
$N=$ number of turns in receiving coil
$r_{n}=$ radius of nth turn in receiving coil ( cm )
The decoder has a sensing threshold of about 0.5 V ; therefore, there is a 0.5 V margin in which induced voltages can be tolerated.

Given the geometry of the receiving coil and an imposed requirement that the induced voltage is, at most, $50 \%$ of the 0.5 V margin at the decoder, a maximum allowable magnetic field is calculated, as shown in Figure 17.


Figure 17. Maximum Allowable External Magnetic Flux Density
For example, at a magnetic field frequency of 1 MHz , the maximum allowable magnetic field of 0.2 kGauss induces a voltage of 0.25 V at the receiving coil. This is about $50 \%$ of the sensing threshold and does not cause a faulty output transition. Similarly, if such an event occurs during a transmitted pulse and is the worst-case polarity, it reduces the received pulse from $>1.0 \mathrm{~V}$ to $0.75 \mathrm{~V}-$ still well above the 0.5 V sensing threshold of the decoder.

Figure 18 shows the magnetic flux density values in terms of more familiar quantities such as maximum allowable current flow at given distances away from the ADM2485 transformers.


Figure 18. Maximum Allowable Current for Various Current-to-ADM2485 Spacings

At combinations of strong magnetic field and high frequency, any loops formed by printed circuit board traces could induce sufficiently large error voltages to trigger the thresholds of succeeding circuitry. Care should be taken in the layout of such traces to avoid this possibility.

## APPLICATIONS INFORMATION

## PC BOARD LAYOUT

The ADM2485 isolated RS-485 transceiver requires no external interface circuitry for the logic interfaces. Power supply bypassing is strongly recommended at the input and output supply pins (see Figure).

Bypass capacitors are most conveniently connected between Pin 3 and $\operatorname{Pin} 4$ for $V_{D D 1}$ and between Pin 15 and Pin 16 for $V_{D D 2}$. The capacitor value should be between $0.01 \mu \mathrm{~F}$ and $0.1 \mu \mathrm{~F}$. The total lead length between both ends of the capacitor and the input power supply pin should not exceed 20 mm .

Bypassing between Pin 1 and Pin 8 and between Pin 9 and Pin 16 should also be considered unless the ground pair on each package side is connected close to the package.


Figure 19. Recommended Printed Circuit Board Layout

In applications involving high common-mode transients, care should be taken to ensure that board coupling across the isolation barrier is minimized. Furthermore, the board layout should be designed such that any coupling that does occur equally affects all pins on a given component side.

Failure to ensure this could cause voltage differentials between pins exceeding the device's absolute maximum ratings, thereby leading to latch-up or permanent damage.

## APPLICATIONS DIAGRAM

The ADM2485 integrates a transformer driver which when used with an external transformer and LDO generates an isolated 5 V power supply, to be supplied between the $\mathrm{V}_{\mathrm{DD} 2}$ and the $\mathrm{GND}_{2}$ pins.

Pins D1 and D2 of the ADM2485 drive a center-tapped transformer T1, A pair of Schottky diodes and a smoothing capacitor are used to create a rectified signal from the secondary winding. The ADP667 linear voltage regulator provides a regulated 5V power supply to the ADM2485's busside circuitry ( $\mathrm{V}_{\mathrm{DD} 2}$ ), as shown in Figure 20.

When the ADM2485 is powered by 3 V on the logic side a 1CT:2.2CT transformer T1 is required to step up the 3 V to 6 V , so that therefore is enough headroom for the ADP667 LDO to
output a regulated 5 V output.
If ADM2485 is powered by 5 V on the logic side a 1CT:1.5CT transformer T 1 is required so that therefore is enough headroom for the ADP667 LDO to output a regulated 5 V output.


Figure 20. Applications Diagram

## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-013AA
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN

Figure 21. 16-Lead Wide-Body Small Outline Package [SOIC]
(RW-16)
Dimensions shown in millimeters

## ORDERING GUIDE

| Model | Data Rate (Mbps) | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- | :--- |
| ADM2485BRWZ $^{1}$ | 16 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 -Lead Wide Body SOIC | RW-16 |
| ADM2485BRWZ-REEL $^{1}$ | 16 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 -Lead Wide Body SOIC | RW-16 |

The addition of an "-RL" suffix designates a 13 " (1000 units) tape and reel option.
${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.


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