W152

Spread Aware™, Eight Output Zero Delay Buffer

Features

- **Spread Aware™—designed to work with SSFTG reference signals**
- **Two banks of four outputs each**
- **Configuration options to halve, double, or quadruple the reference frequency refer to *Table 1* to determine the specific option which meets your multiplication needs**
- **Outputs may be three-stated**
- **Available in 16-pin SOIC package**
- **Extra strength output drive available (-11/-12 versions)**
- **Contact factory for availability information on 16-pin TSSOP**

Key Specifications

Operating Voltage: .... 3.3V±10%

Operating Range: .... 15 MHz < f_{OUTQA} < 140 MHz

Cycle-to-Cycle Jitter: (Refer to *Figure 3*) .... 225 ps

Cycle-to-Cycle Jitter: Frequency Range 25 to140 MHz .... 125 ps

Output to Output Skew: Between Banks ....215 ps

Output to Output Skew: Within Banks (Refer to *Figure 4*) ....100 ps

Total Timing Budget Impact:.......................................555 ps

Max. Phase Error Variation: ....±225 ps

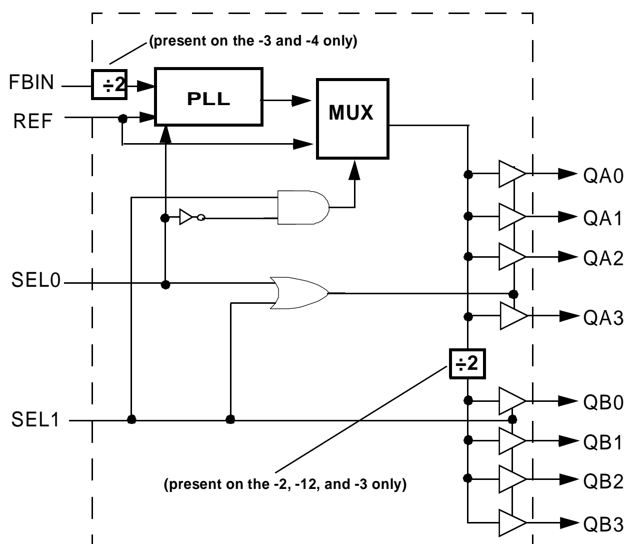
Tracking Skew:..±130 ps

Table 1. Configuration Options

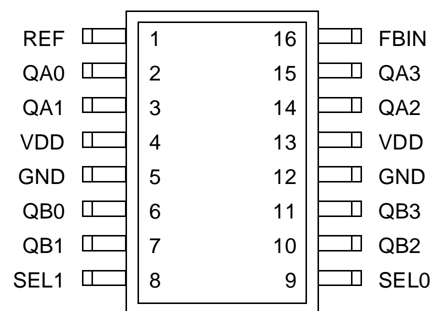
Device	Feedback Signal	QA0:3	QB0:3
W152-1/11[1]	QA0:3 or QB0:3	REFx1	REFx1
W152-2/12[2]	QA0:3	REFx1	REF/2
W152-2/12[2]	QB0:3	REFx2	REFx1
W152-3	QA0:3	REFx2	REFx1
W152-3	QB0:3	REFx4	REFx2
W152-4	QA0:3 or QB0:3	REFx2	REFx2

Notes:
1. W152-11 has stronger output drive than the W152-1.
2. W152-12 has stronger output drive than the W152-2.

Block Diagram



Pin Configuration



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Pin Definitions

Pin Name	Pin No.	Pin Type	Pin Description
REF	1	I	***Reference Input:*** The output signals QA0:3 through QB0:3 will be synchronized to this signal unless the device is programmed to bypass the PLL.
FBIN	16	I	***Feedback Input:*** When programmed to zero delay buffer mode, this input must be fed by one of the outputs (QA0:3 or QB0:3) to ensure proper functionality. If the trace between FBIN and the output pin being used for feedback is equal in length to the traces between the outputs and the signal destinations, then the signals received at the destinations will be synchronized to the REF signal input.
QA0:3	2, 3, 14, 15	O	***Outputs from Bank A:*** The frequency of the signals provided by these pins is determined by the feedback signal connected to FBIN, and the specific W152 option being used. See *Table 2*.
QB0:3	6, 7, 10, 11	O	***Outputs from Bank B:*** The frequency of the signals provided by these pins is determined by the feedback signal connected to FBIN, and the specific W152 option being used. See *Table 2*.
VDD	4, 13	P	***Power Connections:*** Connect to 3.3V. Use ferrite beads to help reduce noise for optimal jitter performance.
GND	5, 12	G	***Ground Connections:*** Connect all grounds to the common system ground plane.
SEL0:1	9, 8	I	***Function Select Inputs:*** Tie to V_{DD} (HIGH, 1) or GND (LOW, 0) as desired per *Table 2*.

Overview

The W152 products are eight-output zero delay buffers. A Phase-Locked Loop (PLL) is used to take a time-varying signal and provide eight copies of that same signal out. The external feedback to the PLL provides outputs in phase with the reference inputs.

Internal dividers exist in some options allowing the user to get a simple multiple (/2, x2, x4) of the reference input, for details see *Table 1*. Because the outputs are separated into two banks, it is possible to provide some combination of these multiples at the same time.

Spread Aware

Many systems being designed now utilize a technology called Spread Spectrum Frequency Timing Generation. Cypress has been one of the pioneers of SSFTG development, and we designed this product so as not to filter off the Spread Spectrum feature of the Reference input, assuming it exists. When a zero delay buffer is not designed to pass the SS feature through, the result is a significant amount of tracking skew which may cause problems in systems requiring synchronization.

For more details on Spread Spectrum timing technology, please see the Cypress application note titled, "EMI Suppression Techniques with Spread Spectrum Frequency Timing Generator (SSFTG) ICs."

Functional Description

Logic inputs provide the user the ability to turn off one or both banks of clocks when not in use, as described in *Table 2*. Disabling a bank of unused outputs will reduce jitter and power consumption, and will also reduce the amount of EMI generated by the W152.

These same inputs allow the user to bypass the PLL entirely if so desired. When this is done, the device no longer acts as a zero delay buffer, it simply reverts to a standard eight-output clock driver.

The W152 PLL enters an auto power-down mode when there are no rising edges on the REF input. In this mode, all outputs are three-stated and the PLL is turned off.

Table 2. Input Logic

SEL1	SEL0	QA0:3	QB0:3	PLL
0	0	Three-State	Three-State	Shutdown
0	1	Active	Three-State	Active, Utilized
1	0	Active	Active	Shutdown, Bypassed
1	1	Active	Active	Active, Utilized

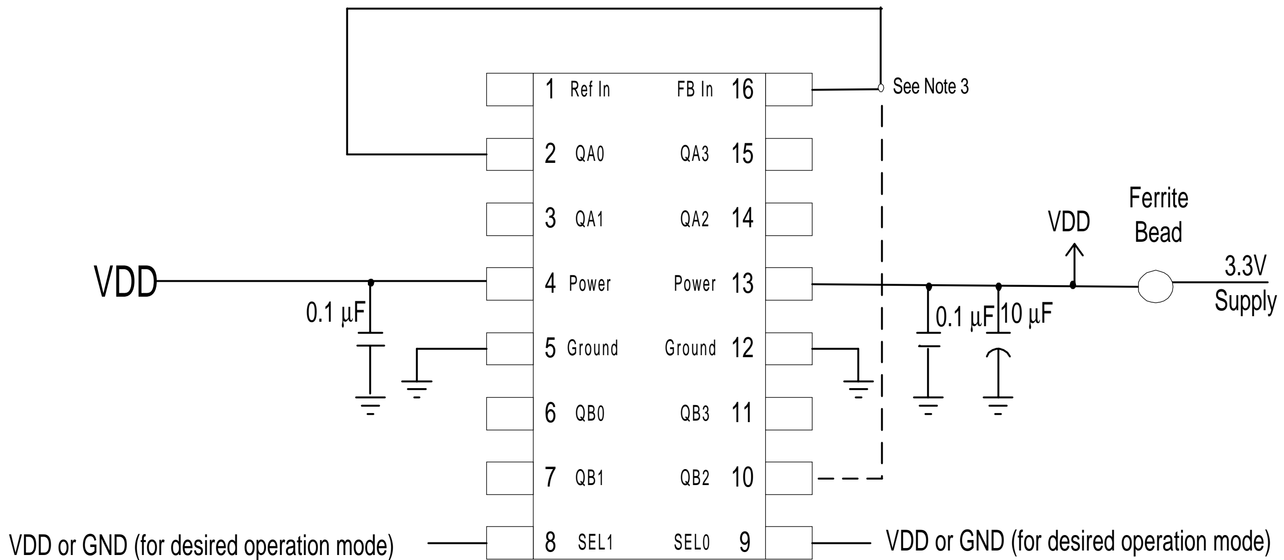


Figure 1. Schematic[3]

Note:
3. Pin 16 needs to be connected to one of the outputs from either bank A or bank B, it should not be connected to both. Pins 2 and 10 are shown here as examples. None of the outputs should be considered aas preferred for the feedback path.

How to Implement Zero Delay

Typically, zero delay buffers (ZDBs) are used because a designer wants to provide multiple copies of a clock signal in phase with each other. The whole concept behind ZDBs is that the signals at the destination chips are all going HIGH at the same time as the input to the ZDB. In order to achieve this, layout must compensate for trace length between the ZDB and the target devices. The method of compensation is described below.

External feedback is the trait that allows for this compensation. The PLL on the ZDB will cause the feedback signal to be in phase with the reference signal. When laying out the board, match the trace lengths between the output being used for feedback and the FBIN input to the PLL.

If it is desirable to either add a little delay, or slightly precede the input signal, this may also be affected by either making the trace to the FBIN pin a little shorter or a little longer than the traces to the devices being clocked.

Inserting Other Devices in Feedback Path

Another nice feature available due to the external feedback is the ability to synchronize signals up to the signal coming from some other device. This implementation can be applied to any device (ASIC, multiple output clock buffer/driver, etc.) which is put into the feedback path.

Referring to *Figure 2*, if the traces between the ASIC/buffer and the destination of the clock signal(s) (A) are equal in length to the trace between the buffer and the FBIN pin, the signals at the destination(s) device will be driven HIGH at the same time the Reference clock provided to the ZDB goes HIGH. Synchronizing the other outputs of the ZDB to the outputs form the ASIC/Buffer is more complex however, as any propagation delay in the ASIC/Buffer must be accounted for.

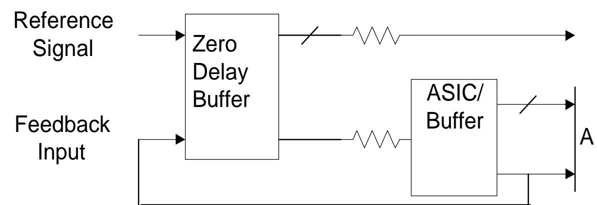


Figure 2. 6 Output Buffer in the Feedback Path

Absolute Maximum Ratings

Stresses greater than those listed in this table may cause permanent damage to the device. These represent a stress rating only. Operation of the device at these or any other conditions above those specified in the operating sections of this specification is not implied. Maximum conditions for extended periods may affect reliability.

Parameter	Description	Rating	Unit
V_{DD}, V_{IN}	Voltage on any pin with respect to GND	–0.5 to +7.0	V
T_{STG}	Storage Temperature	–65 to +150	°C
T_A	Operating Temperature	0 to +70	°C
T_B	Ambient Temperature under Bias	–55 to +125	°C
P_D	Power Dissipation	0.5	W

DC Electrical Characteristics: T_A =0°C to 70°C, V_{DD} = 3.3V ±10%

Parameter	Description	Test Condition	Min.	Typ.	Max.	Unit
I_{DD}	Supply Current	Unloaded, 100 MHz			40	mA
V_{IL}	Input Low Voltage				0.8	V
V_{IH}	Input High Voltage		2.0			V
V_{OL}	Output Low Voltage	I_{OL} = 12 mA (-11, -12) I_{OL} = 8 mA (-1, -2, -3, -4)			0.4	V
V_{OH}	Output High Voltage	I_{OH} = 12 mA (-11, -12) I_{OH} = 8 mA (-1, -2, -3, -4)	2.4			V
I_{IL}	Input Low Current	V_{IN} = 0V			50	µA
I_{IH}	Input High Current	V_{IN} = V_{DD}			50	µA

AC Electrical Characteristics: T_A = 0°C to +70°C, V_{DD} = 3.3V ±10%

Parameter	Description	Test Condition	Min.	Typ.	Max.	Unit
f_{IN}	Input Frequency	Note 3	15		140	MHz
f_{OUT}	Output Frequency	15-pF load[8]	15		140	MHz
t_R	Output Rise Time (-1, -2, -3, -4)	0.8V to 0.8V, 15-pF load		2	2.5	ns
	Output Rise Time (-11, -12)	0.8V to 0.8V, 15-pF load			1.5	ns
t_F	Output Fall Time (-1, -2, -3, -4)	2.0V to 0.8V, 15-pF load		2	2.5	ns
	Output Rise Time (-11, -12)	2.0V to 0.8V, 20-pF load			1.5	ns
t_{ICLKR}	Input Clock Rise Time[4]				4.5	ns
t_{ICLKF}	Input Clock Fall Time[4]				4.5	ns
t_{PD}	FBIN to REF Skew[5, 6]				350	ps
t_{SK}	Output to Output Skew	All outputs loaded equally[10]			215	ps
t_D	Duty Cycle	15-pF load[7, 8]	45	50	55	%
t_{LOCK}	PLL Lock Time	Power supply stable			1.0	ms
t_{JC}	Jitter, Cycle-to-Cycle	Note 9			225	ps

Notes:

3. Input frequency is limited by output frequency range and input to output frequency multiplication factor (which is determined by circuit configuration). See *Table 1*.
4. Longer input rise and fall time will degrade skew and jitter performance.
5. All AC specifications are measured with a 50Ω transmission line.
6. Skew is measured at V_{DD}/2 on rising edges.
7. Duty cycle is measured at V_{DD}/2.
8. For the higher drive -11 and -12, the load is 20 pF.
9. For frequencies above 25 MHz CY - CY = 125 ps.
10. Measured across all outputs. Maximum skew between outputs in the same bank is 100 ps.

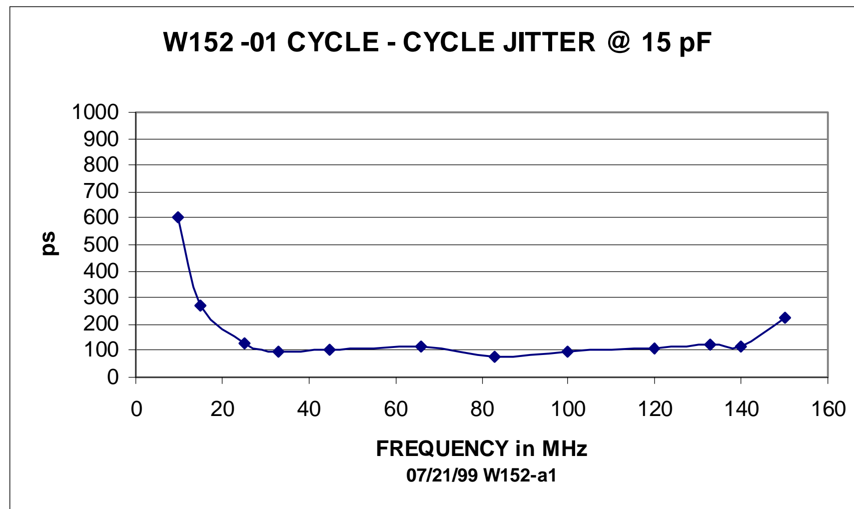


Figure 3. Cycle to Cycle Jitter at 15 pF

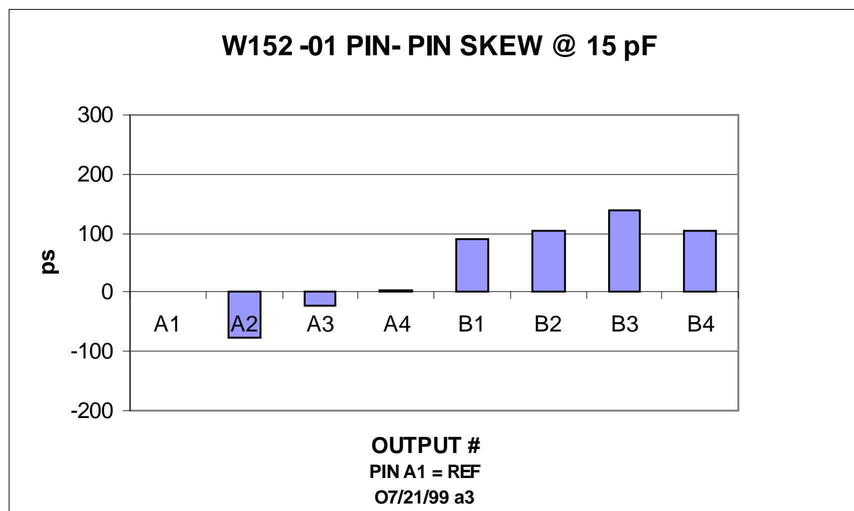


Figure 4. Pin to Pin Skew at 15 pF

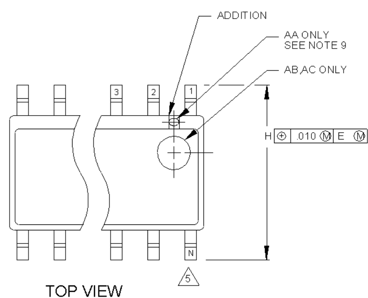
Ordering Information

Ordering Code	Option	Package Name	Package Type
W152	-1, -11, -2, -12, -3, -4	G X	16-pin SOIC (150 mil) 16-pin TSSOP (4.4 mm)

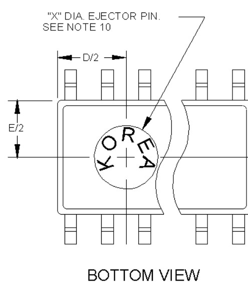
Document #: 38-00786-*B

Package Diagrams

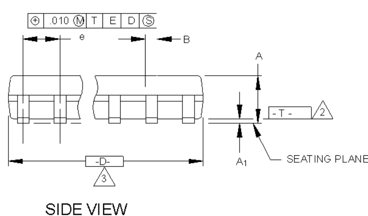
16-Pin Small Outline Integrated Circuit (SOIC, 150 mils)



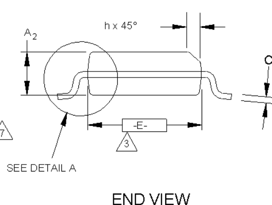
TOP VIEW



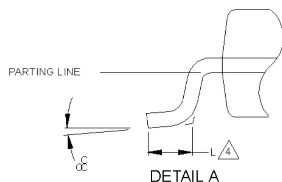
BOTTOM VIEW



SIDE VIEW



END VIEW



DETAIL A

NOTES:

1. MAXIMUM DIE THICKNESS ALLOWABLE IS .015.
2. DIMENSIONING & TOLERANCES PER ANSI.Y14.5M - 1982.
3. "T" IS A REFERENCE DATUM.
4. "D" & "E" ARE REFERENCE DATUMS AND DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS, BUT DOES INCLUDE MOLD MISMATCH AND ARE MEASURED AT THE MOLD PARTING LINE. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.006 INCHES PER SIDE.
5. "L" IS THE LENGTH OF TERMINAL FOR SOLDERING TO A SUBSTRATE.
6. "N" IS THE NUMBER OF TERMINAL POSITIONS.
7. TERMINAL POSITIONS ARE SHOWN FOR REFERENCE ONLY.
8. FORMED LEADS SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITHIN .003 INCHES AT SEATING PLANE.
9. THE APPEARANCE OF PIN #1 I.D ON THE 8 LD IS OPTIONAL, ROUND TYPE ON SINGLE LEADFRAME AND RECTANGULAR TYPE ON MATRIX LEADFRAME.
10. COUNTRY OF ORIGIN LOCATION AND EJECTOR PIN ON PACKAGE BOTTOM IS OPTIONAL AND DEPEND ON ASSEMBLY LOCATION.
11. CONTROLLING DIMENSION: INCHES.

THIS TABLE IN INCHES

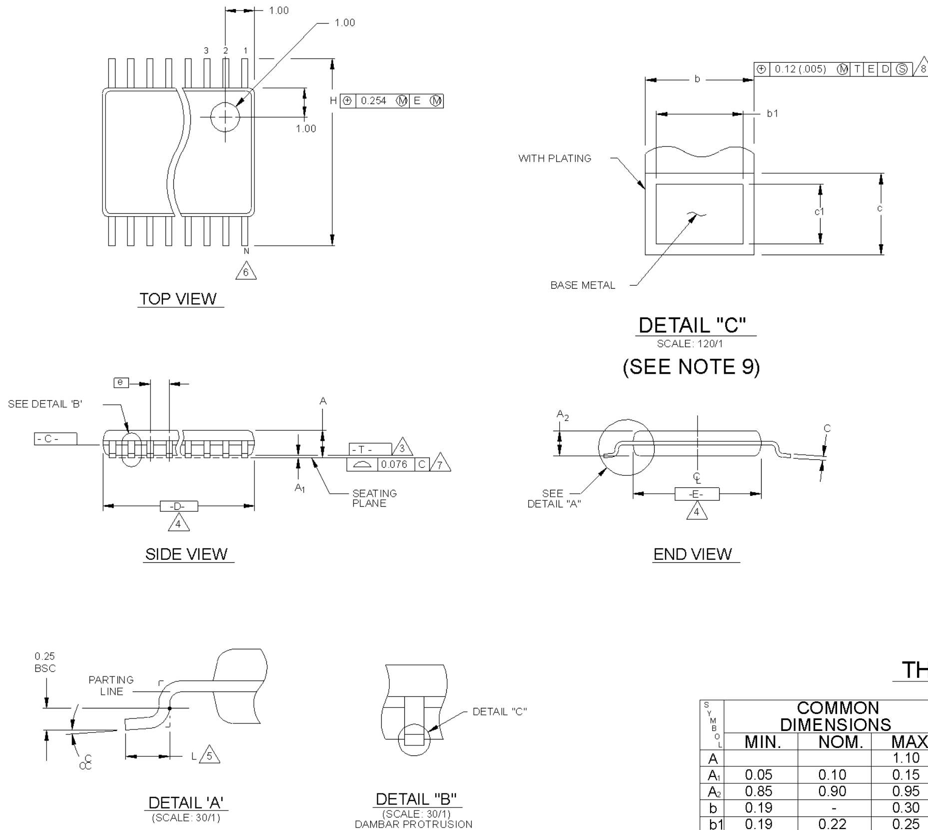
SYMBOL	COMMON DIMENSIONS			NOTE	NOTE VARIATIONS	3			5
						D			N
	MIN.	NOM.	MAX.			MIN.	NOM.	MAX.	
A	.061	.064	.068		AA	.189	.194	.196	8
A_1	.004	.006	.0098		AB	.337	.342	.344	14
A_2	.055	.058	.061		AC	.386	.391	.393	16
B	.0138	.016	.0192						
C	.0075	.008	.0098						
D	SEE VARIATIONS			3					
E	.150	.155	.157						
e	.050 BSC								
H	.230	.236	.244						
h	.010	.013	.016						
L	.016	.025	.035						
N	SEE VARIATIONS			5					
α	0°	5°	8°						
X	.085	.093	.100						

THIS TABLE IN MILLIMETERS

SYMBOL	COMMON DIMENSIONS			NOTE	NOTE VARIATIONS	3			5
						D			N
	MIN.	NOM.	MAX.			MIN.	NOM.	MAX.	
A	1.55	1.63	1.73		AA	4.80	4.93	4.98	8
A_1	0.127	0.15	0.25		AB	8.58	8.69	8.74	14
A_2	1.40	1.47	1.55		AC	9.80	9.93	9.98	16
B	0.35	0.41	0.49						
C	0.19	0.20	0.25						
D	SEE VARIATIONS			3					
E	3.81	3.94	3.99						
e	1.27 BSC								
H	5.84	5.99	6.20						
h	0.25	0.33	0.41						
L	0.41	0.64	0.89						
N	SEE VARIATIONS			5					
α	0°	5°	8°						
X	2.16	2.36	2.54						

Package Diagrams (continued)

16-Pin Thin Shrink Small Outline Package (TSSOP, 4.4 mm)



NOTES:

1. DIE THICKNESS ALLOWABLE IS 0.279±0.0127 (.0110±.0005 INCHES)
2. DIMENSIONING & TOLERANCES PER ANSI.Y14.5M-1982.
3. "T" IS A REFERENCE DATUM.
4. "D" & "E" ARE REFERENCE DATUMS AND DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS, AND ARE MEASURED AT THE PARTING LINE, MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.15mm PER SIDE.
5. DIMENSION IS THE LENGTH OF TERMINAL FOR SOLDERING TO A SUBSTRATE.
6. TERMINAL POSITIONS ARE SHOWN FOR REFERENCE ONLY.
7. FORMED LEADS SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITHIN 0.076mm AT SEATING PLANE.
8. THE LEAD WIDTH DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08mm TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSIONS AND AN ADJACENT LEAD TO BE 0.14mm SEE DETAILS 'B' AND 'C'.
9. DETAIL "C" TO BE DETERMINED AT 0.10 TO 0.25 MM FROM THE LEAD TIP.
10. CONTROLLING DIMENSION: MILLIMETERS.
11. THIS PART IS COMPLIANT WITH JEDEC SPECIFICATION MO-153. VARIATIONS AA, AB, AC, AD AND AE.

THIS TABLE IN MILLIMETERS

SYMBOL	COMMON DIMENSIONS			NOTE	NOTE	4			6
					VARIATIONS	D			N
	MIN.	NOM.	MAX.			MIN.	NOM.	MAX.	
A			1.10		AA	2.90	3.00	3.10	8
A_1	0.05	0.10	0.15		AB	4.90	5.00	5.10	14
A_2	0.85	0.90	0.95		AC	4.90	5.00	5.10	16
b	0.19	-	0.30	8	AD	6.40	6.50	6.60	20
b1	0.19	0.22	0.25		AE	7.70	7.80	7.90	24
c	0.090	-	0.20		AF	9.60	9.70	9.80	28
c1	0.090	0.127	0.135						
D	SEE VARIATIONS			4					
E	4.30	4.40	4.50	4					
e	0.65 BSC								
H	6.25	6.40	6.50						
L	0.50	0.60	0.70	5					
N	SEE VARIATIONS			6					
α	0°	4°	8°						

THIS TABLE IN INCHES

SYMBOL	COMMON DIMENSIONS			NOTE	NOTE	4			6
					VARIATIONS	D			N
	MIN.	NOM.	MAX.			MIN.	NOM.	MAX.	
A			.0433		AA	.114	.118	.122	8
A_1	.002	.004	.006		AB	.193	.197	.201	14
A_2	.0335	.0354	.0374		AC	.193	.197	.201	16
b	.0075	-	.0118	8	AD	.252	.256	.260	20
b1	.0075	.0087	.0098		AE	.303	.307	.311	24
c	.0035	-	.0079		AF	.378	.382	.386	28
c1	.0035	.0050	.0053						
D	SEE VARIATIONS			4					
E	.169	.173	.177	4					
e	.0256 BSC								
H	.246	.252	.256						
L	.020	.024	.028	5					
N	SEE VARIATIONS			6					
α	0°	4°	8°						

VARIATION AF IS DESIGNED BUT NOT TOOLED

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